

**RegML 2016**  
**Class 1**  
**Statistical Learning Theory**

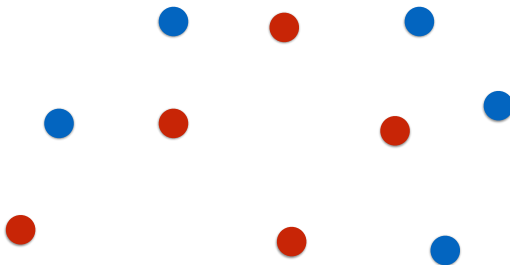
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## All starts with DATA

- ▶ **Supervised:**  $\{(x_1, y_1), \dots, (x_n, y_n)\}$ ,
- ▶ Unsupervised:  $\{x_1, \dots, x_m\}$ ,
- ▶ Semi-supervised:  $\{(x_1, y_1), \dots, (x_n, y_n)\} \cup \{x_1, \dots, x_m\}$

# Learning from examples



**Problem:** given  $S_n = \{(x_1, y_1), \dots, (x_n, y_n)\}$  find  $f(x_{\text{new}}) \sim y_{\text{new}}$

## Setting for the supervised learning problem

- ▶  $X \times Y$  probability space, with measure  $\rho$ .
- ▶  $S_n = (x_1, y_1), \dots, (x_n, y_n) \sim \rho^n$ , i.e. sampled i.i.d.
- ▶  $L : Y \times Y \rightarrow [0, \infty)$ , measurable *loss function*.
- ▶ Expected risk

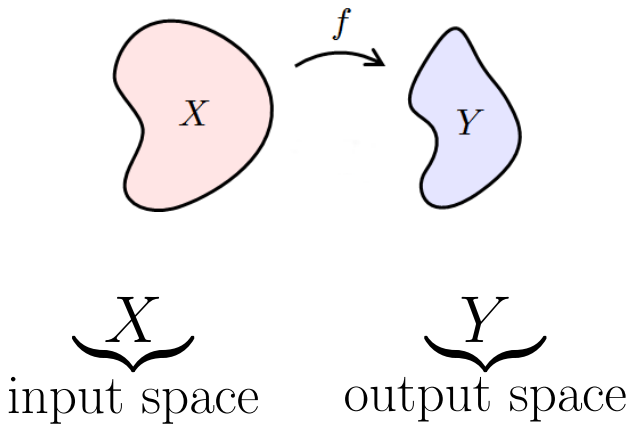
$$\mathcal{E}(f) = \int_{X \times Y} L(y, f(x)) d\rho(x, y).$$

**Problem:** Solve

$$\min_{f: X \rightarrow Y} \mathcal{E}(f),$$

given only  $S_n$  ( $\rho$  fixed, but unknown).

## Data space



# Input space

$X$  input space:

- ▶ linear spaces, e. g.
  - vectors,
  - functions,
  - matrices/operators
  
- ▶ “structured” spaces, e. g.
  - strings,
  - probability distributions,
  - graphs

# Output space

## $Y$ output space

- ▶ linear spaces, e. g.
  - $Y = \mathbb{R}$ , regression,
  - $Y = \{+1, -1\}$ , classification,
  - $Y = \mathbb{R}^T$ , multi-task regression,
  - $Y = \{1, \dots, T\}$ , multi-label classification
  
- ▶ “structured” spaces
  - strings,
  - probability distributions,
  - graphs

## Probability distribution

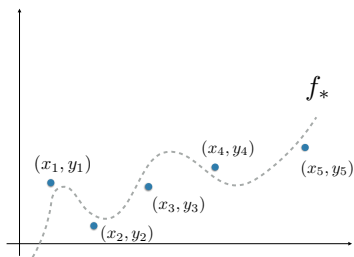
Reflects *uncertainty* and *stochasticity* of the learning problem

$$\rho(x, y) = \rho_X(x)\rho(y|x),$$

- ▶  $\rho_X$  marginal distribution on  $X$ ,
- ▶  $\rho(y|x)$  conditional distribution on  $Y$  given  $x \in X$ .



## Conditional distribution and noise



### Regression

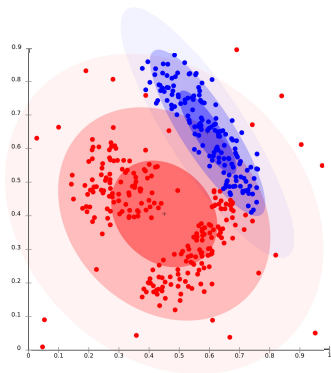
$$y_i = f_*(x_i) + \epsilon_i,$$

- ▶ Let  $f_* : X \rightarrow Y$ , fixed function
- ▶  $\epsilon_1, \dots, \epsilon_n$  zero mean random variables
- ▶  $x_1, \dots, x_n$  random

# Conditional distribution and misclassification

## Classification

$$\rho(y|x) = \{\rho(1|x), \rho(-1|x)\},$$

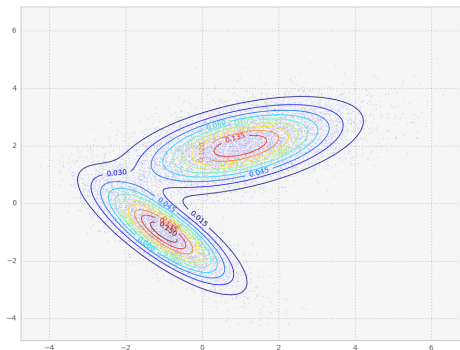


Noise in classification: overlap between the classes

$$\Delta_t = \left\{ x \in X \mid |\rho(1|x) - \rho(-1|x)| \leq t \right\}$$

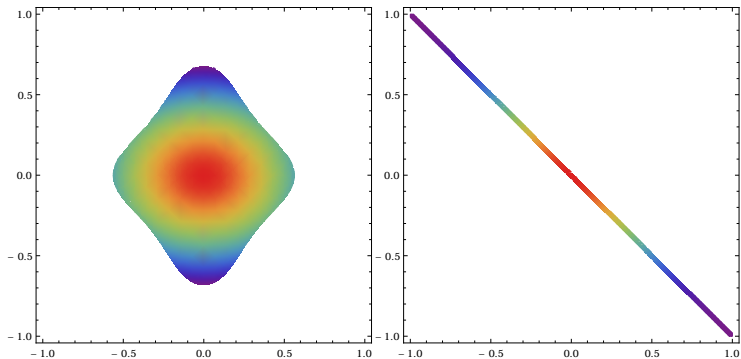
## Marginal distribution and sampling

$\rho_X$  takes into account uneven sampling of the input space



## Marginal distribution, densities and manifolds

$$p(x) = \frac{d\rho_X(x)}{dx} \rightarrow p(x) = \frac{d\rho_X(x)}{d\text{vol}(x)},$$



## Loss functions

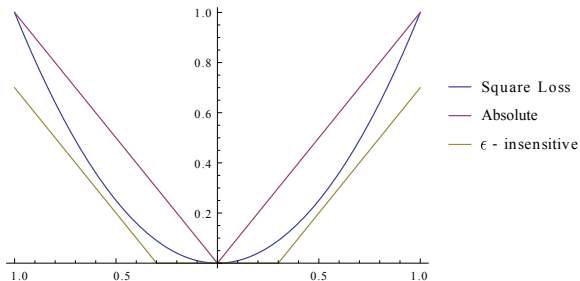
$$L : Y \times Y \rightarrow [0, \infty),$$

- ▶ The cost of predicting  $f(x)$  in place of  $y$ .
- ▶ Part of the problem definition  $\mathcal{E}(f) = \int L(y, f(x))d\rho(x, y)$
- ▶ Measures the *pointwise error*,

## Losses for regression

$$L(y, y') = L(y - y')$$

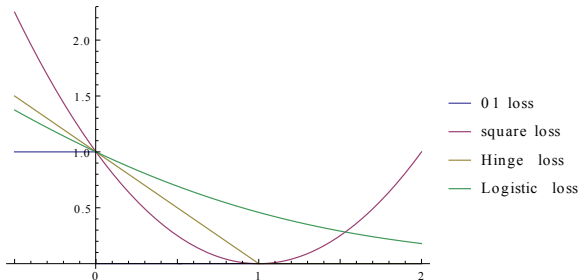
- ▶ Square loss  $L(y, y') = (y - y')^2$ ,
- ▶ Absolute loss  $L(y, y') = |y - y'|$ ,
- ▶  $\epsilon$ -insensitive  $L(y, y') = \max(|y - y'| - \epsilon, 0)$ ,



## Losses for classification

$$L(y, y') = L(-yy')$$

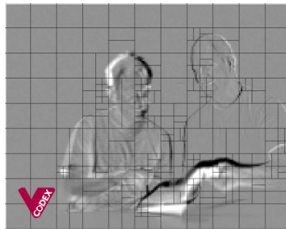
- ▶ 0-1 loss  $L(y, y') = \mathbf{1}_{\{-yy' > 0\}}$
- ▶ Square loss  $L(y, y') = (1 - yy')^2$ ,
- ▶ Hinge-loss  $L(y, y') = \max(1 - yy', 0)$ ,
- ▶ logistic loss  $L(y, y') = \log(1 + \exp(-yy'))$ ,



## Losses for structured prediction

Loss specific for each learning task e. g.

- ▶ Multi-class: square loss, weighted square loss, logistic loss, ...
- ▶ Multi-task: weighted square loss, absolute, ...
- ▶ ...





## Expected risk

$$\mathcal{E}(f) = \mathcal{E}_L(f) = \int_{X \times Y} L(y, f(x)) d\rho(x, y)$$

note that  $f \in \mathcal{F}$  where

$$\mathcal{F} = \{f : X \rightarrow Y \mid f \text{ measurable}\}.$$

**Example**  $Y = \{-1, +1\}$ ,  $L(y, f(x)) = \mathbf{1}_{\{-yf(x) > 0\}}$

$$\mathcal{E}(f) = \mathbb{P}(\{(x, y) \in X \times Y \mid f(x) \neq y\}).$$

## Target function

$$f_\rho = \arg \min_{f \in \mathcal{F}} \mathcal{E}(f),$$

can be derived for many loss functions...

## Target functions in regression

**square loss,**

$$f_{\rho}(x) = \int_Y y d\rho(y|x)$$

**absolute loss,**

$$f_{\rho}(x) = \text{median } \rho(y|x),$$

where

$$\text{median } p(\cdot) = y \quad \text{s.t.} \quad \int_{-\infty}^y t dp(t) = \int_y^{+\infty} t dp(t).$$

## Target functions in classification

**0-1 loss,**

$$f_{\rho}(x) = \mathbf{sign}(\rho(1|x) - \rho(-1|x))$$

**square loss,**

$$f_{\rho}(x) = \rho(1|x) - \rho(-1|x)$$

**logistic loss,**

$$f_{\rho}(x) = \log \frac{\rho(1|x)}{\rho(-1|x)}$$

**hinge-loss,**

$$f_{\rho}(x) = \mathbf{sign}(\rho(1|x) - \rho(-1|x))$$

## Learning algorithms

$$S_n \rightarrow \hat{f}_n = \hat{f}_{S_n}$$

$f_n$  estimates  $f_\rho$  given the observed examples  $S_n$

How to measure the error of an estimator?

## Excess risk

Excess Risk:

$$\mathcal{E}(\hat{f}) - \inf_{f \in \mathcal{F}} \mathcal{E}(f),$$

Consistency: For any  $\epsilon > 0$

$$\lim_{n \rightarrow \infty} \mathbb{P} \left( \mathcal{E}(\hat{f}) - \inf_{f \in \mathcal{F}} \mathcal{E}(f) > \epsilon \right) = 0,$$

## Tail bounds, sample complexity and error bound

- ▶ *Tail bounds:* For any  $\epsilon > 0, n \in \mathbb{N}$

$$\mathbb{P} \left( \mathcal{E}(\hat{f}) - \inf_{f \in \mathcal{F}} \mathcal{E}(f) > \epsilon \right) \leq \delta(n, \mathcal{F}, \epsilon)$$

- ▶ *Sample complexity:* For any  $\epsilon > 0, \delta \in (0, 1]$ , when  $n \geq n_0(\epsilon, \delta, \mathcal{F})$

$$\mathbb{P} \left( \mathcal{E}(\hat{f}) - \inf_{f \in \mathcal{F}} \mathcal{E}(f) > \epsilon \right) \leq \delta,$$

- ▶ *Error bounds:* For any  $\delta \in (0, 1]$ ,  $n \in \mathbb{N}$ , with probability at least  $1 - \delta$ ,

$$\mathcal{E}(\hat{f}) - \inf_{f \in \mathcal{F}} \mathcal{E}(f) \leq \epsilon(n, \mathcal{F}, \delta),$$

## Error bounds and no free-lunch theorem

**Theorem** For any  $\hat{f}$ , there exists a problem for which

$$\mathbb{E}(\mathcal{E}(\hat{f})) - \inf_{f \in \mathcal{F}} \mathcal{E}(f) > 0$$



## No free-lunch theorem continued

**Theorem** For any  $\hat{f}$ , there exists a  $\rho$  such that

$$\mathbb{E}(\mathcal{E}(\hat{f})) - \inf_{f \in \mathcal{F}} \mathcal{E}(f) > 0$$

$\mathcal{F} \rightarrow \mathcal{H}$  Hypothesis space

## Hypothesis space

$$\mathcal{H} \subset \mathcal{F}$$

E.g.  $X = \mathbb{R}^d$

$$\mathcal{H} = \left\{ f(x) = \langle w, x \rangle = \sum_{j=1}^d w_j x_j, \mid w \in \mathbb{R}^d, \forall x \in X \right\}$$

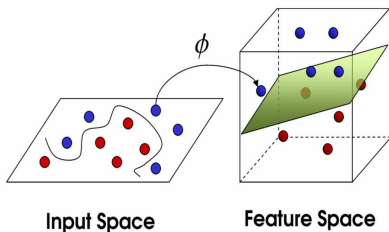
then  $\mathcal{H} \simeq \mathbb{R}^d$ .

## Finite dictionaries

$$D = \{\phi_i : X \rightarrow \mathbb{R} \mid i = 1, \dots, p\}$$

$$\mathcal{H} = \left\{ f(x) = \sum_{j=1}^p w_j \phi_j(x) \mid w_1, \dots, w_p \in \mathbb{R}, \forall x \in X \right\}$$

$$f(x) = w^\top \Phi(x), \quad \Phi(x) = (\phi_1(x), \dots, \phi_p(x))$$



# This class

## Learning theory ingredients

- ▶ Data space/distribution
- ▶ Loss function, risks and target functions
- ▶ Learning algorithms and error estimates
- ▶ Hypothesis space

## Next class

- ▶ Regularized learning algorithm: penalization
- ▶ Statistics and computations
- ▶ Nonparametrics and kernels