# MLCC 2018 Regularization Networks I: Linear Models

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## About this class

- $\triangleright$  We introduce a class of learning algorithms based on Tikhonov regularization
- $\triangleright$  We study computational aspects of these algorithms .

## Empirical Risk Minimization (ERM)

- $\triangleright$  Empirical Risk Minimization (ERM): probably the most popular approach to design learning algorithms.
- $\triangleright$  General idea: considering the empirical error

$$
\hat{\mathcal{E}}(f) = \frac{1}{n} \sum_{i=1}^{n} \ell(y_i, f(x_i)),
$$

as a proxy for the expected error

$$
\mathcal{E}(f) = \mathbb{E}[\ell(y, f(x))] = \int dx dy p(x, y) \ell(y, f(x)).
$$

# The Expected Risk is Not Computable

Recall that

 $\blacktriangleright \ell$  measures the price we pay predicting  $f(x)$  when the true label is y

 $\blacktriangleright$   $\mathcal{E}(f)$  cannot be directly computed, since  $p(x, y)$  is unknown

## From Theory to Algorithms: The Hypothesis Space

To turn the above idea into an actual algorithm, we:

- $\blacktriangleright$  Fix a suitable hypothesis space H
- $\blacktriangleright$  Minimize  $\hat{\mathcal{E}}$  over H

 $H$  should allow feasible computations and be *rich*, since the complexity of the problem is not known a priori.

### Example: Space of Linear Functions

The simplest example of  $H$  is the space of linear functions:

$$
H = \{ f : \mathbb{R}^d \to \mathbb{R} \; : \; \exists w \in \mathbb{R}^d \text{ such that } f(x) = x^T w, \; \forall x \in \mathbb{R}^d \}.
$$

 $\blacktriangleright$  Each function f is defined by a vector w

$$
\blacktriangleright f_w(x) = x^T w.
$$

## Rich Hs May Require Regularization

- If H is rich enough, solving ERM may cause overfitting (solutions highly dependent on the data)
- $\blacktriangleright$  Regularization techniques restore stability and ensure generalization

## Tikhonov Regularization

Consider the Tikhonov regularization scheme,

$$
\min_{w \in \mathbb{R}^d} \hat{\mathcal{E}}(f_w) + \lambda \|w\|^2 \tag{1}
$$

It describes a large class of methods sometimes called Regularization Networks.

# The Regularizer

- $\blacktriangleright$   $||w||^2$  is called regularizer
- $\blacktriangleright$  It controls the stability of the solution and prevents overfitting
- $\blacktriangleright$   $\lambda$  balances the error term and the regularizer

### Loss Functions

- $\triangleright$  Different loss functions  $\ell$  induce different classes of methods
- $\triangleright$  We will see common aspects and differences in considering different loss functions
- $\triangleright$  There exists no general computational scheme to solve Tikhonov Regularization
- $\triangleright$  The solution depends on the considered loss function

#### The Regularized Least Squares Algorithm

Regularized Least Squares: Tikhonov regularization

$$
\min_{w \in \mathbb{R}^D} \hat{\mathcal{E}}(f_w) + \lambda \|w\|^2, \quad \hat{\mathcal{E}}(f_w) = \frac{1}{n} \sum_{i=1}^n \ell(y_i, f_w(x_i)) \tag{2}
$$

Square loss function:

$$
\ell(y, f_w(x)) = (y - f_w(x))^2
$$

We then obtain the RLS optimization problem (linear model):

$$
\min_{w \in \mathbb{R}^D} \frac{1}{n} \sum_{i=1}^n (y_i - w^T x_i)^2 + \lambda w^T w, \quad \lambda \ge 0.
$$
 (3)

### Matrix Notation

- $\blacktriangleright$  The  $n \times d$  matrix  $X_n$ , whose rows are the input points
- $\blacktriangleright$  The  $n \times 1$  vector  $Y_n$ , whose entries are the corresponding outputs.

With this notation,

$$
\frac{1}{n}\sum_{i=1}^{n}(y_i - w^T x_i)^2 = \frac{1}{n}||Y_n - X_n w||^2.
$$

### Gradients of the ER and of the Regularizer

By direct computation,

Gradient of the empirical risk w. r. t.  $w$ 

$$
-\frac{2}{n}X_n^T(Y_n - X_nw)
$$

Gradient of the regularizer w. r. t.  $w$ 

 $2w$ 

## The RLS Solution

By setting the gradient to zero, the solution of RLS solves the linear system

$$
(X_n^T X_n + \lambda n I)w = X_n^T Y_n.
$$

 $\lambda$  controls the *invertibility* of  $(X_n^T X_n + \lambda nI)$ 

## Choosing the Cholesky Solver

- $\triangleright$  Several methods can be used to solve the above linear system
- $\blacktriangleright$  Cholesky decomposition is the method of choice, since

 $X_n^T X_n + \lambda I$ 

is symmetric and positive definite.

# Time Complexity

Time complexity of the method :

- $\blacktriangleright$  Training:  $O(nd^2)$  (assuming  $n >> d$ )
- $\blacktriangleright$  Testing:  $O(d)$

# Dealing with an Offset

For linear models, especially in low dimensional spaces, it is useful to consider an offset:

$$
w^T x + b
$$

How to estimate  $b$  from data?

### Idea: Augmenting the Dimension of the Input Space

- $\triangleright$  Simple idea: augment the dimension of the input space, considering  $\tilde{x} = (x, 1)$  and  $\tilde{w} = (w, b)$ .
- $\triangleright$  This is fine if we do not regularize, but if we do then this method tends to prefer linear functions passing through the origin (zero offset), since the regularizer becomes:

$$
\|\tilde{w}\|^2 = \|w\|^2 + b^2.
$$

### Avoiding to Penalize the Solutions with Offset

We want to regularize considering only  $\|w\|^2$ , without penalizing the offset.

The modified regularized problem becomes:

$$
\min_{(w,b)\in\mathbb{R}^{D+1}}\frac{1}{n}\sum_{i=1}^n(y_i - w^T x_i - b)^2 + \lambda \|w\|^2.
$$

### Solution with Offset: Centering the Data

It can be proved that a solution  $w^*, b^*$  of the above problem is given by

$$
b^* = \bar{y} - \bar{x}^T w^*
$$

where

$$
\bar{y} = \frac{1}{n} \sum_{i=1}^{n} y_i
$$

$$
\bar{x} = \frac{1}{n} \sum_{i=1}^{n} x_i
$$

### Solution with Offset: Centering the Data

 $w^*$  solves

$$
\min_{w \in \mathbb{R}^D} \frac{1}{n} \sum_{i=1}^n (y_i^c - w^T x_i^c)^2 + \lambda \|w\|^2.
$$

where 
$$
y_i^c = y - \bar{y}
$$
 and  $x_i^c = x - \bar{x}$  for all  $i = 1, ..., n$ .

Note: This corresponds to centering the data and then applying the standard RLS algorithm.

### Introduction: Regularized Logistic Regression

Regularized logistic regression: Tikhonov regularization

$$
\min_{w \in \mathbb{R}^d} \hat{\mathcal{E}}(f_w) + \lambda \|w\|^2, \quad \hat{\mathcal{E}}(f_w) = \frac{1}{n} \sum_{i=1}^n \ell(y_i, f_w(x_i)) \tag{4}
$$

With the *logistic loss function*:

$$
\ell(y, f_w(x)) = \log(1 + e^{-y f_w(x)})
$$

### The Logistic Loss Function



Figure: Plot of the logistic regression loss function

# Minimization Through Gradient Descent

- $\blacktriangleright$  The logistic loss function is differentiable
- $\triangleright$  The candidate to compute a minimizer is the gradient descent (GD) algorithm

## Regularized Logistic Regression (RLR)

- $\triangleright$  The regularized ERM problem associated with the logistic loss is called regularized logistic regression
- $\triangleright$  Its solution can be computed via gradient descent
- $\blacktriangleright$  Note:

$$
\nabla \hat{\mathcal{E}}(f_w) = \frac{1}{n} \sum_{i=1}^n x_i \frac{-y_i e^{-y_i x_i^T w_{t-1}}}{1 + e^{-y_i x_i^T w_{t-1}}} = \frac{1}{n} \sum_{i=1}^n x_i \frac{-y_i}{1 + e^{y_i x_i^T w_{t-1}}}
$$

#### RLR: Gradient Descent Iteration

For  $w_0 = 0$ , the GD iteration applied to

$$
\min_{w \in \mathbb{R}^d} \hat{\mathcal{E}}(f_w) + \lambda \|w\|^2
$$

is

$$
w_{t} = w_{t-1} - \gamma \underbrace{\left(\frac{1}{n} \sum_{i=1}^{n} x_{i} \frac{-y_{i}}{1 + e^{y_{i}x_{i}^{T}w_{t-1}}} + 2\lambda w_{t-1}\right)}_{a}
$$

for  $t = 1, \ldots T$ , where

 $a = \nabla(\hat{\mathcal{E}}(f_w) + \lambda ||w||^2)$ 

## Logistic Regression and Confidence Estimation

- $\triangleright$  The solution of logistic regression has a probabilistic interpretation
- $\blacktriangleright$  It can be derived from the following model

$$
p(1|x) = \underbrace{\frac{e^{x^T w}}{1 + e^{x^T w}}}_{h}
$$

where  $h$  is called *logistic function*.

 $\triangleright$  This can be used to compute a *confidence* for each prediction

### Support Vector Machines

#### Formulation in terms of Tikhonov regularization:

$$
\min_{w \in \mathbb{R}^d} \hat{\mathcal{E}}(f_w) + \lambda \|w\|^2, \quad \hat{\mathcal{E}}(f_w) = \frac{1}{n} \sum_{i=1}^n \ell(y_i, f_w(x_i)) \tag{5}
$$

With the Hinge loss function:



$$
\ell(y, f_w(x)) = |1 - yf_w(x)|_+
$$

# A more classical formulation (linear case)

$$
w^* = \min_{w\in\mathbb{R}^d}\frac{1}{n}\sum_{i=1}^n|1-y_iw^\top x_i|_++\lambda\|w\|^2
$$
 with  $\lambda=\frac{1}{C}$ 

# A more classical formulation (linear case)

$$
w^* = \min_{w \in \mathbb{R}^d, \xi_i \ge 0} \|w\|^2 + \frac{C}{n} \sum_{i=1}^n \xi_i \quad \text{subject to}
$$

$$
y_i w^\top x_i \ge 1 - \xi_i \quad \forall i \in \{1 \dots n\}
$$

## A geometric intuition - classification

In general do you have many solutions



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Intuitively I would choose an "equidistant" line



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# Maximum margin classifier

I want the classifier that

- $\blacktriangleright$  classifies perfectly the dataset
- $\blacktriangleright$  maximize the distance from its closest examples



### Point-Hyperplane distance

How to do it mathematically? Let  $w$  our separating hyperplane. We have

 $x = \alpha w + x_1$ 



# Margin

An hyperplane  $w$  well classifies an example  $\left(x_i, y_i\right)$  if

▶ 
$$
y_i = 1
$$
 and  $w^\top x_i > 0$  or\n\n $\triangleright y_i = -1$  and  $w^\top x_i < 0$ \n\ntherefore  $x_i$  is well classified iff  $y_i w^\top x_i > 0$ \n\nMargin:  $m_i = y_i w^\top x_i$ \n\nNote that  $x_\perp = x - \frac{y_i m_i}{\|w\|} w$ 

### Maximum margin classifier definition

I want the classifier that

- $\blacktriangleright$  classifies perfectly the dataset
- $\blacktriangleright$  maximize the distance from its closest examples

$$
w^* = \max_{w \in \mathbb{R}^d} \min_{1 \le i \le n} d(x_i, w)^2 \quad \text{subject to}
$$

$$
m_i > 0 \quad \forall i \in \{1 \dots n\}
$$

Let call  $\mu$  the smallest  $m_i$  thus we have

$$
w^* = \max_{w \in \mathbb{R}^d} \min_{1 \le i \le n, \mu \ge 0} ||x_i|| - \frac{(x_i^\top w)^2}{||w||^2} \text{ subject to}
$$

$$
y_i w^\top x_i \ge \mu \quad \forall i \in \{1 \dots n\}
$$

that is

$$
w^* = \max_{w \in \mathbb{R}^d} \min_{\mu \ge 0} -\frac{\mu^2}{\|w\|^2} \quad \text{subject to}
$$

$$
y_i w^\top x_i \ge \mu \quad \forall i \in \{1 \dots n\}
$$

$$
w^* = \max_{w \in \mathbb{R}^d, \mu \ge 0} \frac{\mu^2}{\|w\|^2} \quad \text{subject to}
$$
\n
$$
y_i w^\top x_i \ge \mu \quad \forall i \in \{1 \dots n\}
$$
\nNote that if  $y_i w^\top x_i \ge \mu$ , then  $y_i (\alpha w)^\top x_i \ge \alpha \mu$  and  $\frac{\mu^2}{\|w\|^2} = \frac{(\alpha \mu)^2}{\|\alpha w\|^2}$  for any  $\alpha \ge 0$ . Therefore we have to fix the scale parameter, in particular we choose  $\mu = 1$ .

$$
w^* = \max_{w \in \mathbb{R}^d} \frac{1}{\|w\|^2} \quad \text{subject to}
$$

$$
y_i w^\top x_i \ge 1 \quad \forall i \in \{1 \dots n\}
$$

$$
w^* = \min_{w \in \mathbb{R}^d} ||w||^2 \text{ subject to}
$$
  

$$
y_i w^\top x_i \ge 1 \quad \forall i \in \{1 \dots n\}
$$

### What if the problem is not separable?

We relax the constraints and penalize the relaxation



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We relax the constraints and penalize the relaxation

$$
w^* = \min_{w \in \mathbb{R}^d, \xi_i \ge 0} \|w\|^2 + \frac{C}{n} \sum_{i=1}^n \xi_i \quad \text{subject to}
$$

$$
y_i w^\top x_i \ge 1 - \xi_i \quad \forall i \in \{1 \dots n\}
$$

where  $C$  is a penalization parameter for the average error  $\frac{1}{n} \sum_{i=1}^n \xi_i.$ 



### Dual formulation

It can be shown that the solution of the SVM problem is of the form

$$
w = \sum_{i=1}^{n} \alpha_i y_i x_i
$$

where  $\alpha_i$  are given by the solution of the following quadratic programming problem:

$$
\max_{\alpha \in \mathbb{R}^n} \quad \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i,j=1}^n y_i y_j \alpha_i \alpha_j x_i^T x_j \quad i = 1, \dots, n
$$
\n
$$
\text{subj to} \quad \alpha_i \ge 0
$$

- $\blacktriangleright$  The solution requires the estimate of n rather than D coefficients
- $\triangleright$   $\alpha_i$  are often sparse. The input points associated with non-zero coefficients are called support vectors

# Wrapping up

Regularized Empirical Risk Minimization

$$
w^* = \min_{w \in \mathbb{R}^d} \frac{1}{n} \sum_{i=1}^n \ell(y_i, w^\top x_i) + \lambda \|w\|^2
$$

Examples of Regularization Networks

$$
\blacktriangleright \ell(y,t) = (y-t)^2
$$
 (Square loss) leads to Least Squares

- ►  $\ell(y, t) = log(1 + e^{-yt})$  (Logistic loss) leads to Logistic Regression
- $I(x, t) = |1 yt|_+$  (Hinge loss) leads to Maximum Margin Classifier

### Next class

... beyond linear models!